Convex Optimization Part 2: Gradient descent (more)

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POSTECH

26 Sep 2022

## Admin

#### Attendance

▶ The university policy requires students to attend > 3/4 of a course to claim the credit. Please record your attendance using the app "포스텍 전자출결".

Assignment 1

due by this Friday

## Strong convexity

f is strongly convex with parameter  $\alpha > 0$  if, for all x, y and  $t \in [0, 1]$ ,

$$f(tx + (1-t)y) \le tf(x) + (1-t)f(y) - \frac{\alpha}{2}t(1-t)||x-y||_2^2$$

A stronger version of convexity

For f being  $\alpha\mbox{-strongly convex}$  is equivalent to the following:

$$f(x) - \frac{\alpha}{2} ||x||_2^2$$
 is convex.

For twice differentiable f this means  $\nabla^2 f(x) \succeq \alpha I$ .

A consequence of  $\alpha\text{-strong convexity}$ 

$$f(y) \ge f(x) + \langle \nabla f(x), y - x \rangle + \frac{\alpha}{2} \|y - x\|^2 \qquad \forall x, y$$

*i.e.*, a quadratic lower bound on f.

Consequence of quadratic lower bound

Bound on suboptimality

$$\frac{\alpha}{2} \|x - x^*\|^2 \le f(x) - f(x^*) \le \frac{1}{2\alpha} \|\nabla f(x)\|_2^2$$

▶ The right-hand inequality is a.k.a. Polyak-Łojasiewicz (PL) inequality.

#### Proof.

The proof is done similarly as for smoothness.

Coercivity of gradient

### Coercivity

If f is  $\alpha$ -strongly convex, then

$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \ge \alpha \|x - y\|_2^2 \qquad \forall x, y$$

• a.k.a. strong monotonicity of 
$$\nabla f$$
.

### Proof.

The proof follows by adding the quadratic lower bounds with x, y switched.

## Extension of co-coercivity

For f being  $\alpha\text{-strongly convex and }\beta\text{-smooth, the co-coercivity of gradient extends to}$ 

$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \ge \frac{\alpha \beta}{\alpha + \beta} \|x - y\|_2^2 + \frac{1}{\alpha + \beta} \|\nabla f(x) - \nabla f(y)\|_2^2 \qquad \forall x, y \in \mathbb{R}$$

**Proof.** First, f being  $\alpha$ -strongly convex means the following is convex.

$$g(x) = f(x) - \frac{\alpha}{2} \|x\|_2^2$$

Thus,

$$\begin{split} 0 &\leq \langle \nabla g(x) - \nabla g(y), x - y \rangle & \text{(monotonicity of } g) \\ &= \langle \nabla f(x) - \nabla f(y), x - y \rangle - \alpha \|x - y\|_2^2 & \text{(def. of } g) \\ &\leq (\beta - \alpha) \|x - y\|_2^2 & \text{(}\beta\text{-smoothness)} \end{split}$$

which shows that g is  $(\beta - \alpha)$ -smooth (from the first and last lines). Then writing out co-coercivity of  $\nabla g$  (and rearranging terms) will finish the proof.

# Convergence for smooth and strongly convex functions

#### Theorem

For  $\beta$ -smooth and  $\alpha$ -strongly convex functions, gradient descent with the step size  $\eta = 2/(\alpha + \beta)$  after T iterations satisfies

$$f(x_{T+1}) - f^* \le \rho^T \frac{\beta R^2}{2}$$

where  $\rho = \left(\frac{\kappa-1}{\kappa+1}\right)^2$  with  $\kappa = \beta/\alpha$  and  $R = \|x_1 - x^*\|_2$ .

- This achieves the linear convergence rate of  $\mathcal{O}(\rho^t)$ .
- The number of iterations to reach  $\epsilon$ -accuracy is  $\mathcal{O}(\log(1/\epsilon))$ .
- Big  $\kappa$  leads to slow convergence.

#### Proof.

For GD with step size  $\eta=2/(\alpha+\beta)$  we can write

$$\begin{aligned} \|x_{t+1} - x^*\|_2^2 &= \|x_t - \frac{2}{\alpha + \beta} \nabla f(x_t) - x^*\|_2^2 \\ &= \|x_t - x^*\|_2^2 - \frac{4}{\alpha + \beta} \langle \nabla f(x_t), x_t - x^* \rangle + \left(\frac{2}{\alpha + \beta}\right)^2 \|\nabla f(x_t)\|_2^2 \\ &\leq \left(\frac{\alpha - \beta}{\alpha + \beta}\right)^2 \|x_t - x^*\|_2^2 \end{aligned}$$

where  $\kappa$  the last inquality follows from the extension of co-coercivity. Expanding on t

$$||x_{t+1} - x^*||_2^2 \le \rho^t ||x_1 - x^*||_2^2$$

where  $\rho = \left(\frac{\kappa-1}{\kappa+1}\right)^2$  with  $\kappa = \beta/\alpha$ . Further using the suboptimality bound we derived previously will finish the proof.

# Any questions?